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1 Beam shaping to enhance zero group velocity Lamb
2 mode generation in a composite plate and
3 nondestructive testing application

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11 **Abstract**

Zero group velocity (ZGV) Lamb modes have already shown their potential in nondestructive testing applications as they are sensitive to the sample structural characteristics. In this paper, we first consider an aluminum sample to validate a method based on the beam shaping of the generation laser. This method is proven to enhance ZGV Lamb modes in aluminum, and then advantageously applied to a composite material plate. Finally, based on the proposed method, scanning the sample over healthy and flawed zones demonstrates the ability to detect subsurface flaws.

12 *Keywords:* Laser ultrasonics, Composite materials, Zero Group Velocity
13 Lamb modes, NDT

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14 1. Introduction

15 Laser ultrasonics is a more and more widespread nondestructive testing
16 method as it shows specific advantages compared to conventional ultrasonic
17 methods based on transducers or EMATs. Particularly, it has a high spatial
18 resolution, a large bandwidth, and it is non-contact [1]. Thanks to these fea-
19 tures, laser ultrasonic techniques allow characterizing the mechanical prop-
20 erties and/or evaluating the structural health of materials, even where the
21 tested samples present complex geometry and/or are subjected to extreme
22 conditions such as high temperatures [2]. Up to now, applications of laser
23 ultrasonic methods have already proved their potential in nondestructive
24 testing of composite materials. They have been implemented successfully to
25 detect delaminations with a propagative Lamb waves analysis [3] or by laser
26 tapping [4]. They have also the ability to detect fiber breakage or matrix
27 cracking via the scanning laser source technique [5] or even porosity thanks
28 to an ultrasonic spectroscopy method [6].

29 Guided waves have been used in composite samples testing and evalua-
30 tion because of their ability to detect a defect at a long propagation distance
31 from the acoustic source position. Yet, the defect position is hard to pre-
32 cisely estimate at a single interface at any position through the laminate [3].
33 As well, a lateral position estimation needs methods with a transducer raster
34 scan like the SAFT method [7] or transducer arrays like the topological imag-
35 ing technique [8]. For ten years, some specific non-propagative Lamb modes
36 called zero group velocity (ZGV) Lamb modes have been studied and already
37 applied to defect detection. Considering a dispersion curve representing the
38 angular frequency ω as a function of the wave number k , these specific modes

39 are located in the points of a non-zero wave number k where the slope of this
40 curve is horizontal, i.e. $d\omega/dk = 0$. Characterized by a high quality factor,
41 these modes are used for instance to measure thickness variations due to
42 corrosion, to detect disbonding or to determine elastic constants [9, 10]. A
43 method based on the ZGV Lamb modes offers the advantages of being local
44 and having a spatial resolution of the order of the plate thickness [10]. One
45 objective of this article is to report on the effect of a flaw in a composite
46 plate on ZGV Lamb modes.

47 The challenges to address when generating ZGV Lamb modes in com-
48 posite plates are numerous. Firstly, the composite plates usually have a low
49 damage threshold. For instance, the sample used in this paper showed fiber
50 whitening at about 5 MW.cm^{-2} with a 1064 nm-wavelength laser, whereas
51 the threshold for aluminum in the same experimental conditions is about 50
52 MW.cm^{-2} [11]. Secondly, as composite surfaces are matt and diffusive for
53 light, ultrasonic waves are hardly detectable using non-contact optical tech-
54 niques. Thirdly, quality factors of ZGV Lamb modes are strongly reduced
55 because of the resin viscoelasticity leading to a strong sound attenuation in
56 composite plates. Note that ZGV Lamb modes could even not exist, regard-
57 ing the anisotropic mechanical properties of the material; nevertheless, this
58 is out of the focus of this paper.

59 In this work, elastic waves are generated in an aluminum plate or a com-
60 posite plate by a pulsed laser and detected using an interferometer. By
61 varying the focusing of the pump laser beam, it is possible to favor the
62 generation of either the propagating modes or the ZGV modes in the plate.
63 Especially, considering a circular laser spot as the thermoelastic source, ZGV

64 Lamb modes are efficiently excited when the spot radius is about the plate
65 thickness [12]. It is first shown that ZGV Lamb modes can be enhanced
66 or reduced in an aluminum plate thanks to a specific beam shaping of the
67 generation laser [13–17]. Then, the same method is advantageously applied
68 to the healthy zone of a composite plate. Finally, a damaged region of the
69 same composite plate is considered and the influences of the flaw on the
70 ZGV Lamb modes are analyzed. Before going into details, the mechanical
71 properties of the tested sample and the experimental setups are introduced.

72 **2. Mechanical properties of the tested sample and experimental** 73 **setups**

74 **This section is devoted to the analysis of the influence of flaws on ZGV**
75 **Lamb modes in a plate made of composite material. As the setup is based**
76 **on a beam-shaping mask to selectively generate a specific ZGV mode, it is**
77 **important to know the mechanical properties of the tested material in order**
78 **to design the beam-shaping mask.** We will show that the optimal geometrical
79 properties of the beam-shaping mask for a particular ZGV mode generation
80 depend on the ZGV wavelength in the sample. In the framework of indus-
81 trial nondestructive testing (NDT), mechanical properties of the composite
82 materials are already well characterized. Hence, the wavelengths of the ZGV
83 modes that can be generated **in the sample are known.** Here the mechan-
84 ical properties of the composite sample were first characterized in order to
85 determine an interesting ZGV mode and then to make the appropriate beam-
86 shaping mask.

87 In order to predict the dispersion curve of the composite plate, both the
88 density and the elastic constants have to be determined. First, the volu-

89 metric mass density of the composite sample has been estimated thanks to
 90 Archimedes principle to be $\rho_{comp} \approx 1540 \text{ kg.m}^{-3}$. Second, the elastic con-
 91 stants have been determined thanks to a method explained in Refs. [18]
 92 and [19]. Based on appropriate A-scans, plane wavefronts are synthesized
 93 by summing the signals with suitable delays. By changing the synthesized
 94 propagation angle, quasi-longitudinal and quasi-transversal time of flights are
 95 semi-automatically recorded. Finally, the theoretical slowness curve that fits
 96 the experimental one is determined, thanks to a minimization method. This
 97 leads to the following estimation of the elastic constants: $C_{11} = 13.4 \text{ GPa}$,
 98 $C_{12} = 3.00 \text{ GPa}$, $C_{22} = 21.36 \text{ GPa}$, and $C_{55} = 3.64 \text{ GPa}$. Note that these
 99 constants have been obtained by assuming that the composite plate is trans-
 100 versely isotropic relative to an axis normal to the surface. **The composite**
 101 **plate is a carbon fiber-epoxy composite, composed of 10 plies of 300 μm -thick**
 102 **each, oriented as [45/0/0/45/0/45/0/45/0/45]. Thanks to the SAFE method,**
 103 **the composite plate structure was confirmed to be transversely isotropic. Fi-**
 104 **nally, from the measured plate thickness, $d_{comp} \approx 3.2 \text{ mm}$, the dispersion**
 105 **curves have been calculated and are displayed in Fig. 1. As one could find in**
 106 **literature [20, 21], ZGV Lamb mode can occur in anisotropic material and**
 107 **the wavelength of the first ZGV Lamb mode in our composite plate (cf. ver-**
 108 **tical arrow in Fig. 1 is here estimated with a precision that is sufficient for**
 109 **the method we propose: $\lambda_{ZGV}^{comp} \approx 15.3 \text{ mm}$.**

110 Due to the low damage threshold of composite materials, the choice has
 111 been done to experimentally use an extended line source instead of a circular
 112 spot, in order to lower the source power density on the sample while keeping
 113 sufficiently large displacement amplitude. Theoretically, using an infinitely

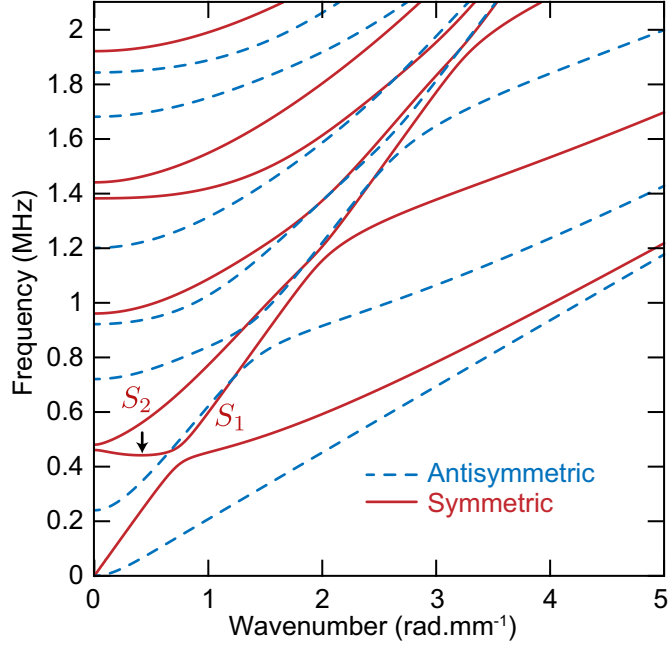


Figure 1: (color online) Dispersion curves of the symmetric (solid line) and antisymmetric (dashed line) Lamb modes calculated in a 3.2-mm-thick composite plate. The first ZGV mode is shown by the vertical arrow and has a wavelength of $\lambda_{ZGV}^{comp} \approx 15.3$ mm.

114 long and thin thermoelastic line source, the amplitude of the surface displace-
 115 ment due to a ZGV Lamb mode as a function of the distance from the line
 116 source is a pure cosine function, since it results from the interference of two
 117 counter-propagative Lamb modes having the same wave number, i.e. of the
 118 form $e^{jk_{ZGV}x}$ and $e^{-jk_{ZGV}x}$. In the case of a finite line source, the amplitude
 119 varies as an intermediate function between the pure cosine function and a
 120 Bessel function [22], the latter standing for the theoretical spatial distribu-
 121 tion of ZGV Lamb modes in the case of a point surface source [12]. In order
 122 to selectively generate the first ZGV Lamb mode and to increase the total in-
 123 cident laser power while keeping the power density constant, we propose here

124 to use multiple finite line sources using an appropriate beam-shaping mask.
125 As illustrated in Fig. 2, using the beam-shaping mask allows the generation
126 laser beam to be shaped with periodic slits whose spacing matches the ZGV
127 wavelength, thereby producing a constructive interference of the ZGV Lamb
128 modes generated by each line source. Note that the laser transient grating
129 technique[13–15] is another efficient technique to selectively generate elastic
130 guided waves with a given wavelength. The use of an optical mask instead of
131 the laser transient grating technique has been mainly chosen for the reason of
132 experimental simplicity. Achieving a transient laser grating with such large
133 period would have indeed required the laser beams to be crossed with a really
134 small angle (about 2.10^{-3} deg), which was technically difficult to reach with
135 a good precision.

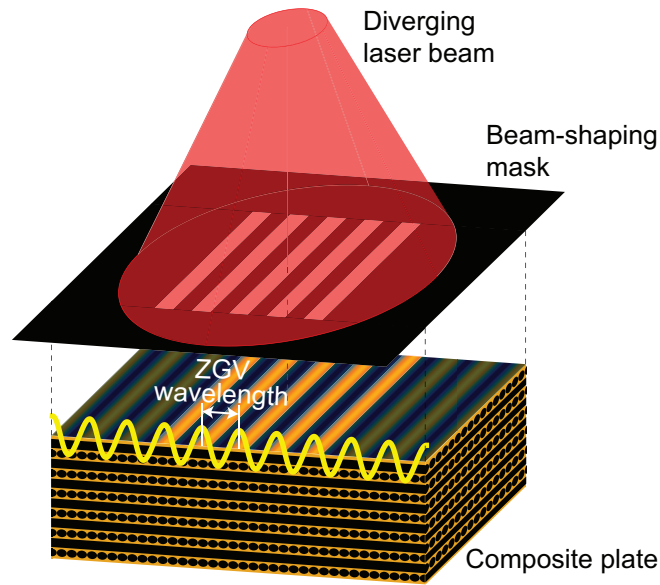


Figure 2: (color online) Illustration of the ZGV Lamb mode generation using a beam-shaping mask. The generation laser beam is shaped with periodic slits whose spacing matches the ZGV wavelength.

136 In order to analyze the ZGV Lamb mode generation using a shaped laser
137 beam, **the experimental setup shown in Fig. 3 has been implemented.** The
138 generation laser is an Nd:YAG laser (Spitlight Compact 400, InnoLas Laser
139 GmbH, Germany) emitting 10 ns pulses at 1064 nm. The pulse energy is
140 limited to a few tens of mJ in order to remain below the damage threshold
141 and to avoid fiber whitening. This limitation of the laser energy is performed
142 using two polarizing beam splitters (PBS) and a half-wave plate ($\lambda/2$) as
143 **shown** in Fig. 3. Thanks to a negative lens, the whole beam shaping mask
144 is illuminated by the generation laser. This mask consists of a series of
145 transparent and opaque patterns (Fig. 2) printed on transparency films by
146 a laser printer. Two identical masks are placed one after the other in the
147 close vicinity of the plate in order to obtain a sufficient contrast. The normal
148 surface displacement due to ultrasonic waves is detected on the other side of
149 the sample by a two-wave mixing (TWM) interferometer (LU-TWM-ASGA,
150 Tecnar Canada) whose bandwidth ranges from about 1 MHz to 40 MHz
151 [23]. Note that the bandpass spectrum of the interferometer filter is smooth
152 and still allows to detect displacement with frequency component down to
153 about 300 kHz. The TWM is using a CW Nd:YAG laser, the beam of which
154 is guided through an optical fiber to the TWM head including a neutral
155 density filter and the focusing/collecting lens. The TWM head is mounted
156 on a motorized linear stage so that the detection point is scannable over the
157 sample. A second motorized linear stage can also be used to scan the sample
158 in front of fixed generation pattern and detection point. Since generation
159 and detection of elastic waves are on opposite sides, this setup is referred to
160 as the transmission setup in the following.

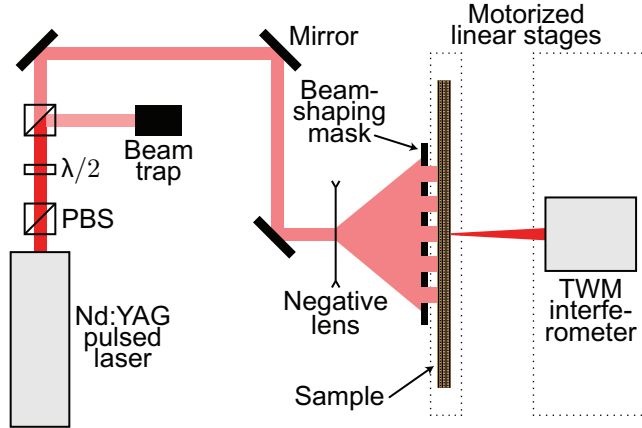


Figure 3: (color online) Schematics of the experimental transmission setup.

161 A second setup has been used in this study, with generation and detection
 162 on the same side, which is referred to as the reflection setup in the following.
 163 It is identical to the transmission setup, except that both generation laser
 164 beam and TWM laser beam illuminate the same side of the sample, and
 165 that the generation laser beam is frequency doubled in order not to dazzle
 166 the TWM interferometer photodiode that is sensitive to 1064 nm radiation.
 167 This setup can particularly be useful for a robot inspection and can give
 168 additional information for a flaw characterization as it will be discussed in the
 169 following: where the transmission setup detects a flaw without information
 170 on its in-depth position, we will see that the reflection setup is able to give
 171 information on the flaw position with respect to the depth.

172 Before applying the proposed method to the detection of a flaw in a
 173 composite plate, it is first proposed to focus on the interest of using a beam-
 174 shaping mask to enhance the ZGV Lamb modes in two samples: first, an
 175 aluminum plate for trivial evidence, and then a composite plate.

176 **3. ZGV Lamb modes enhancement in aluminum and composite**
177 **plates**

178 In order to validate preliminary results obtained with the transmission
179 setup shown in Fig. 3, Fig. 4 presents the experimental results obtained in
180 an 4.1 mm-thick aluminum plate using a single thermoelastic line source of
181 dimensions 4.1 x 20 mm². Figs. 4(a)-(b) are slightly saturated in order to
182 improve readability.

183 The time domain B-scan [Fig. 4(a)] represents the normal surface dis-
184 placement amplitude as a function of time and the TWM head position.
185 The signals have been registered over 200 μ s with the TWM head position
186 ranging from -50 mm to +50 mm with a 0.5 mm step. Two different kinds
187 of modes are visible: (i) the propagating modes starting at the origin in time
188 and space, and (ii) the ZGV Lamb modes that are visible in time after the
189 propagating modes. The ZGV modes are evidenced by a succession of max-
190 ima and minima in time and space, typical of the single frequency and the
191 interferential nature of the ZGV modes.

192 The frequency domain B-scan [Fig. 4(b)] represents the spectral ampli-
193 tude module of each A-scan constituting the time domain B-scan as a func-
194 tion of the TWM head position. Each spectrum constituting the frequency
195 domain B-scan has been calculated over the whole corresponding A-scan. At
196 the first, i.e. lowest, expected ZGV Lamb mode frequency, $f_{ZGV}^{Al} \approx 694$ kHz,
197 there is a maxima and minima succession in space that is typical of ZGV
198 Lamb modes obtained with a thermoelastic line source. When zooming at
199 the ZGV frequency [Fig. 4(c)], the first ZGV peak amplitude as a func-
200 tion of the TWM head position (solid) shows the expected theoretical shape

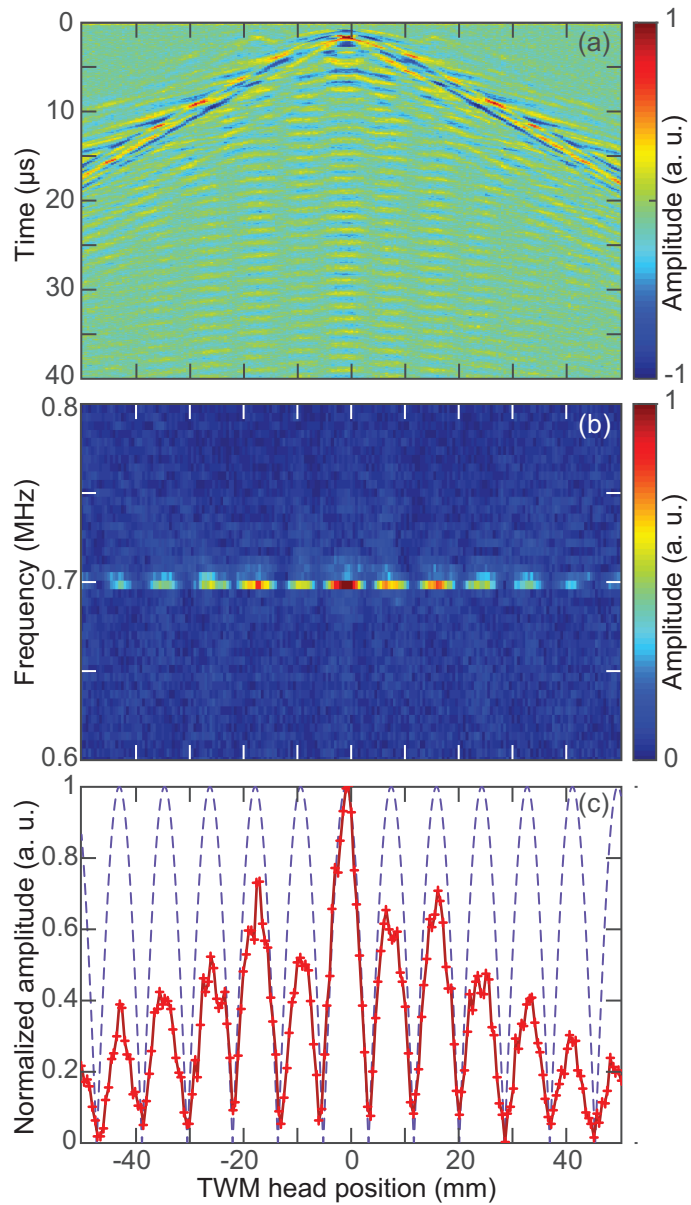


Figure 4: (color online) The thermoelastic source is a line $4.1 \times 20 \text{ mm}^2$: (a) time domain and (b) frequency domain B-scans as a function of the TWM head position. (c) First ZGV peak amplitude vs. TWM head position: experimental (solid) and theoretical (dashed) curves.

201 (dashed), especially regarding the minima. As expected theoretically, the
 202 amplitude of the experimental curve decays with the distance from the line
 203 source position because of the line source finite dimensions.

204 It is now proposed to compare this result obtained with a single line
 205 source to the results obtained with a shaped source composed of lines spaced
 206 by either λ_{ZGV}^{Al} or $\lambda_{ZGV}^{Al}/2$. Figure 5 presents the amplitude of the first ZGV
 207 peak as a function of the TWM head position when the thermoelastic source
 208 is made of: a single line (solid), multiple lines spaced by λ_{ZGV}^{Al} (dashed),
 209 and multiple lines spaced by $\lambda_{ZGV}^{Al}/2$ (dash-dotted). The Frobenius norm
 210 (Euclidian norm) of each normal displacement field is used to normalize each
 211 corresponding curve in Fig. 5, in order for the changes in the absorbed laser
 212 power between the different cases to be compensated.

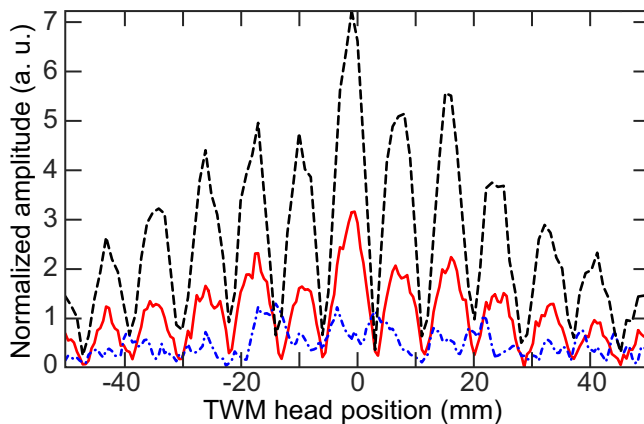


Figure 5: (color online) Normalized first ZGV peak amplitude vs. TWM head position when the thermoelastic source is a single line (solid), multiple lines spaced by λ_{ZGV}^{Al} (dashed) and multiple lines spaced by $\lambda_{ZGV}^{Al}/2$ (dash-dotted).

213 When the lines are spaced by λ_{ZGV}^{Al} , the ZGV Lamb modes are enhanced:
 214 they interfere constructively. On the contrary, when the lines are spaced

215 by $\lambda_{ZGV}^{Al}/2$, the ZGV Lamb mode amplitudes are reduced: they interfere
 216 destructively. As expected, a mask consisting of slits spaced by the ZGV
 217 wavelength enhances the ZGV Lamb modes generation in aluminum com-
 218 pared to a mask consisting of a single slit. The interest of this beam-shaping
 219 method being demonstrated in a metal plate, it is now examined in the more
 220 challenging case of a composite plate.

221 The beam-shaping mask used with the composite plate consists of three
 222 slits spaced by λ_{ZGV}^{comp} . Figures 6(a)-(c) show the experimental results. Fig-
 223 ure 6(a) stands for the time domain B-scan, while Fig. 6(b) shows the fre-
 224 quency domain B-scan. Figures 6(a)-(b) are slightly saturated in order to
 225 improve readability. The amplitude of the first ZGV peak with respect to the
 226 TWM head position obtained for the three-line source (thick line) is com-
 227 pared to the same amplitude obtained with a single line source (thin line)
 228 in Fig. 6(c). The ZGV peak amplitudes in Fig. 6(c) are normalized follow-
 229 ing the same method as the one described for aluminum. **The comparison**
 230 **between the thin and thick lines in Fig. 5(c) clearly demonstrates that the**
 231 **ZGV peak is almost not observable when one slit is used. This emphasizes**
 232 **that it is preferable to use three slits rather than one for the investigation of**
 233 **a composite plate in order to increase the generation efficiency of the ZGV**
 234 **mode and to get a sufficiently large signal to noise ratio for this particular**
 235 **mode. Note that it is not the case for the Aluminum, where the ZGV mode**
 236 **is well detectable when using one slit (cf. Fig. 4).**

237 The time domain B-scan [Fig. 6(a)] highlights the propagating modes
 238 and we slightly see the ZGV Lamb modes. The frequency domain B-scan
 239 [Fig. 6(b)] points out the ZGV Lamb modes at the frequency $f_{ZGV}^{comp} \approx 0.480$ MHz,

240 which is confirmed by Fig. 6(c). Indeed, as ZGV peaks correspond to energy
 241 peaks, they are expected to be spaced by half the ZGV wavelength, that
 242 is to say that ZGV peaks are expected to be located in the middle of each
 243 illuminated slits as well as centrally located between two adjacent slits. As
 244 Fig. 6(c) shows these peaks on the slits location (under black arrows) and
 245 centrally located between two adjacent slits (under gray arrows), this result
 246 tends to prove the enhancement of the ZGV mode in the composite plate
 247 thanks to the proposed beam-shaping mask.

248 In order to obtain Fig. 6(c), the ZGV peak amplitude was measured as the
 249 maximum spectral amplitude module between 0.475 MHz and 0.485 MHz.
 250 This frequency range can be related to a possible sample thickness variation
 251 since the product of the ZGV mode frequency f_{ZGV} by the sample thickness is
 252 constant. Hence, the average ZGV frequency $(f_{ZGV})_0$ and the ZGV frequency
 253 variation Δf_{ZGV} on the one hand, and the average sample thickness d_0 and
 254 the sample thickness variation Δd on the other hand, are related to each
 255 other:

$$256 \quad \frac{\Delta d}{d_0} = -\frac{\Delta f_{ZGV}}{(f_{ZGV})_0}. \quad (1)$$

257 The range [0.475-0.485] MHz leads to a thickness variation Δd of about
 258 $\pm 33 \mu\text{m}$. This sample thickness variation is very small and it is consistent
 259 with the precision of the sample fabrication process.

260 As the beam-shaping method is validated to enhance ZGV Lamb modes
 261 in the composite plate, a suitable mask with slits spaced by λ_{ZGV} is now
 262 used for an NDT application.

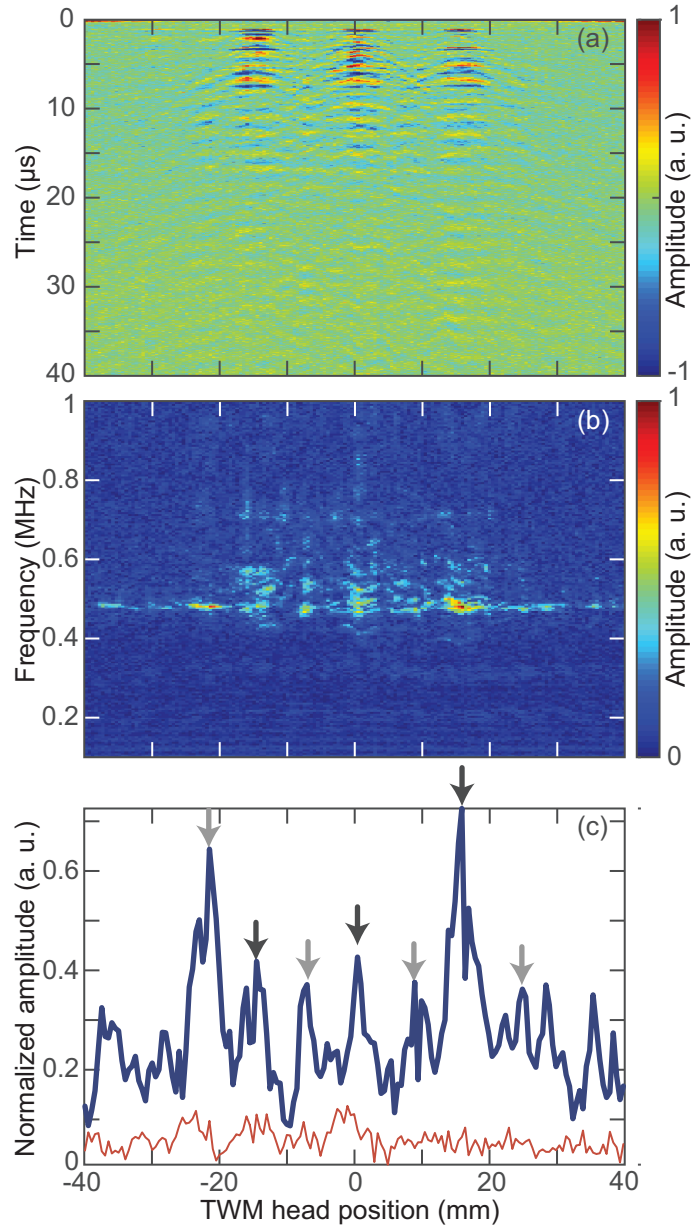


Figure 6: (color online) Results obtained in the composite plate with a thermoelastic source made of three lines: (a) time domain and (b) frequency domain B-scans vs. TWM head position. (c) Normalized amplitude of the first ZGV peak vs. TWM head position (thick line) compared with the result obtained with a single line source (thin line).

263 **4. NDT application in a composite plate**

264 The reflection setup described in Sec. 2 is now used to scan the composite
265 plate in front of both spatially fixed Nd:YAG frequency doubled laser beam
266 and TWM interferometer beam. The former is shaped by a mask having three
267 slits spaced by λ_{ZGV}^{comp} and the latter being focused to a point in the middle
268 of the beam shaping mask (middle line). As quickly explained in Sec. 2, the
269 choice of using a reflection setup instead of the so-far used transmission setup
270 is twofold: (i) this is closer to industrial applicability, and (ii) the flaw in the
271 tested sample is such that, at the flaw location, there is no direct transmission
272 of the elastic waves through the flaw, making the lateral detection of the flaw
273 easy but not the in-depth location. We will see that using a reflection setup
274 can lead to this in-depth characterization of the flaw.

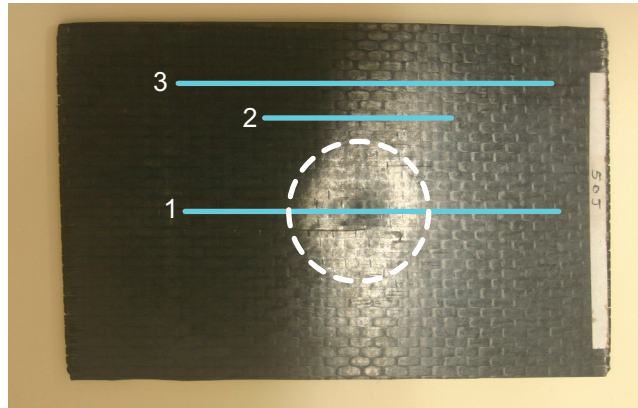


Figure 7: (color online) Composite sample and representation of the scan lines (solid). Dashed white line circle: maximum size of the flaw observed optically.

275 The composite sample presented in Fig. 7 has been impacted by a 50 J
276 centered shock. The 50 J shock was obtained thanks to the drop of a hemi-
277 spherical mass with a diameter of 25 mm. The sample was clamped on a

278 bearing having a 40 mm-diameter hole, centered with respect to the drop
 279 mass axis. The first scan line (line 1) crosses the impact whereas the second
 280 scan line (line 2) is near the impact location and the third scan line (line
 281 3) is far from the impact location. Within all these scans, the line sources
 282 composing the shaped thermoelastic source were perpendicular to the scan
 283 direction. Regarding line 3, note that the shaped thermoelastic source is at
 284 least 5 mm away from both the plate edge and the impact location, whatever
 285 the plate position during the scan is.

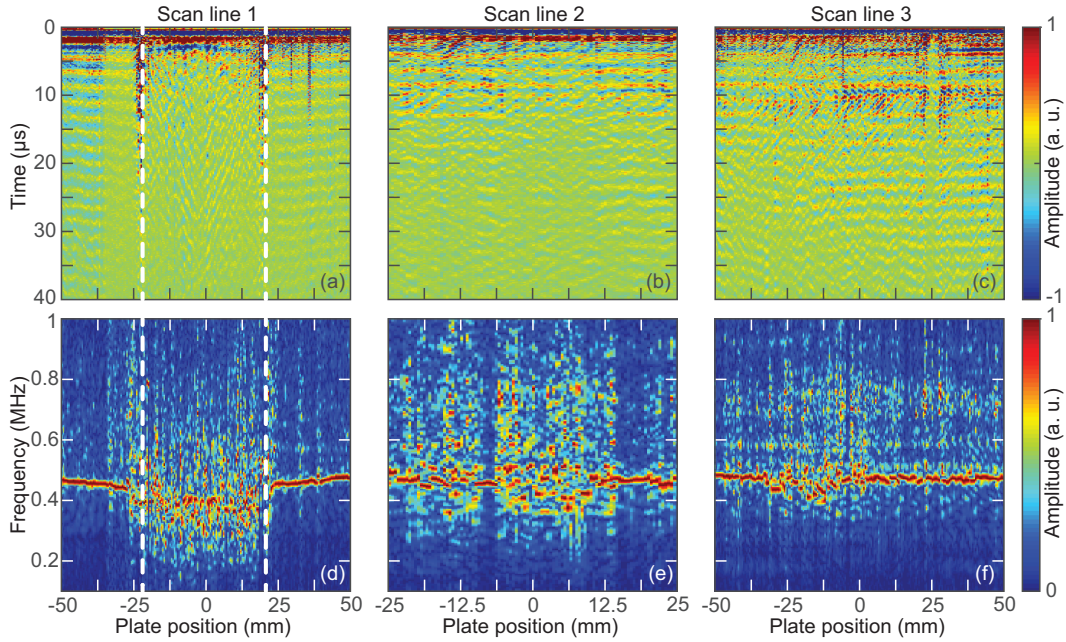


Figure 8: (color online) Time domain B-scans of the composite plate when the scan line is: line 1 across the impact location (a), line 2 near the impact location (b), and line 3 far from the impact location (c). The related frequency domain B-scans obtained with a Hann time window (respectively d, e and f). Dashed white lines: maximum dimension of the flaw observed optically.

286 The time domain B-scan signals have been registered over 200 μs with

287 the plate position ranging from -50 mm to $+50$ mm [Fig. 8(a) and Fig. 8(c)]
288 or from -25 mm to $+25$ mm [Fig. 8(b)] with a 0.5 mm step. Each A-scan for
289 a given plate position is numerically post-processed in order to have a zero
290 mean value over the useful signal duration, i.e. from 10 μ s to 100 μ s. The
291 frequency domain B-scans have then been calculated over the whole time
292 domain signals filtered by a Hann time window ranging from 0 μ s to 100 μ s
293 in order to emphasize the ZGV Lamb modes. The spectrum amplitude for a
294 given plate position is normalized to its maximum.

295 In Fig. 8(a), the time domain B-scan across the impact location high-
296 lights the impact edges marked by the dashed white lines (cf. also Fig. 7).
297 Moreover, regular successions of maxima and minima in time, representative
298 of ZGV oscillations, can be observed outside of the impact location (in a
299 healthy zone) whereas the signal appears disturbed inside the impact loca-
300 tion. The time domain B-scans near the impact location and far from the
301 impact location [Fig. 8(b) and Fig. 8(c), respectively] show minor changes
302 with the plate position and no flaw is clearly evidenced.

303 The frequency domain B-scan across the impact location [Fig. 8(d)] also
304 clearly highlights the impact as only the ZGV frequency is visible outside
305 the impact location whereas on the impact location the dominant frequency
306 components are spread out over the range $\sim 200 - 800$ kHz and show quick
307 variations in space. Let us also notice that the ZGV frequency decreases
308 almost linearly when the signal measurement gets closer to the impact. As
309 the product f_{ZGV} by the thickness is constant, this shows that either the
310 plate thickness increases with the impact vicinity (the 50 J impact has lead
311 to a bulge at the vicinity of the impact) or the elastic moduli diminish.

312 The frequency domain B-scan near the impact location [Fig. 8(e)] also shows
313 changing multiple frequency components between -5 mm and $+15$ mm that
314 could be due to the impact vicinity. Moreover, farther from the impact
315 location, i.e. between -25 mm and -10 mm, multiple frequency components
316 also appear whereas this zone should be healthy. The frequency domain B-
317 scan far from the impact location [Fig. 8(f)] shows that the main frequency
318 component is the ZGV frequency below -30 mm and above 0 mm; these zones
319 can thus be considered as quasi-healthy zones. On the contrary, between
320 -30 mm and 0 mm, a hidden flaw is detected. This confirms the previous
321 result [Fig. 8(e)] highlighting a flaw on a zone that should be healthy.

322 These results have been compared to the composite plate inspection ob-
323 tained with a system called LUCIE, the technical specifications of which are
324 gathered in Ref. [24]. Note that the minimum laser fluence delivered by the
325 pump laser (CO_2 , 270 mJ, 100 ns) in the LUCIE system is $1.5 \text{ MW}\cdot\text{cm}^{-2}$,
326 which is below the damage threshold of the composite. Signals are gathered
327 at a fast rate by the LUCIE system thanks to its scan head which includes
328 both the pump laser and the probe laser used for the interferometric mea-
329 surement of the sample surface velocity. Figure 9 represents the C-scan
330 inspection of the composite plate consisting in measuring the ratio of two
331 ultrasonic echo amplitudes as a function of the position on the plate: the ra-
332 tio of the amplitudes of the second ultrasonic echo detected (acoustic waves
333 reflected by the rear surface of the plate or by a defect) to the first ultrasonic
334 echo detected (corresponding to the surface expansion due to laser absorp-
335 tion). Note that the ratio can be done after filtering the collected raw data
336 with a selective band-pass filter. LUCIE's data post-processing may also give

337 an image (not shown in this paper) of the time of flight difference between
 338 the first and the second detected acoustic echo, although this image is not
 339 precise for in-depth localization of defects close to the surface. The presented
 340 scan (Fig. 9) shows two major results. First, the 50 J impact is very well
 341 identified by the centered zone that shows the lowest value. Second, on the
 342 healthy zone scanned previously (cf. line 3 in Fig. 7), the ratio has either
 343 values in $[4.55-9.75]$ % that should be indicative of a real healthy zone or
 344 weak values lower than 3.25 % that are indicative of a flaw. This last result
 345 confirms the presence of the hidden flaw detected previously along the scan
 346 line 3 by the method proposed by the authors.

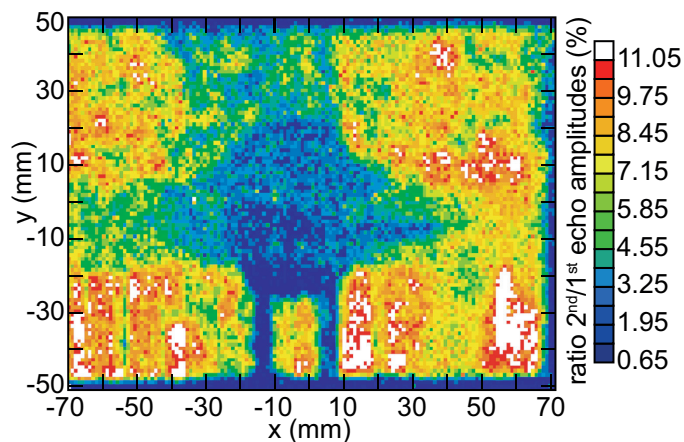


Figure 9: (color online) C-scan inspection of the composite plate obtained with the LUCIE system: ratio of the second ultrasonic echo amplitude to the first ultrasonic echo amplitude

347 Using the experimental transmission setup, a supplementary scan has
 348 been done along the scan line 1, the results of which are not presented in
 349 this paper. The observation is that, at the flaw location, no elastic wave is
 350 directly transmitted. This observation probably means that the 50 J impact

351 produced a delamination inside the composite plate.

352 Let us consider that the impact produced a delamination inside the com-
353 posite plate, hence splitting the plate into a minimum of two thinner plates
354 one above the other. If we assume that laser generated ultrasonic waves
355 interact only with the top plate, several mechanisms can explain why the
356 frequency domain B-scans show multiple frequency components on the de-
357 lamination location. A given frequency component different from the ZGV
358 mode frequency of the plate can be due to a membrane resonance effect [25]
359 or to a local defect resonance [26]. It could even be due to another ZGV mode
360 frequency associated to a smaller thickness than the one of the plate. A flaw
361 resonance frequency f_r can be estimated by assuming a circular clamped
362 membrane:

$$363 \quad f_r = \frac{1.88h}{d^2} \sqrt{\frac{E}{\rho(1-\nu^2)}}, \quad (2)$$

364 where h and d are the flaw depth and diameter respectively, and E , ρ and ν
365 are the sample Young's modulus, density and Poisson ratio respectively.

366 Assuming that the characteristic frequency is due to a circular flaw res-
367 onance and using the following material parameters: $h = 300 \mu\text{m}$ (a ply
368 thickness), $E = 15 \text{ GPa}$, $\rho = 1540 \text{ kg/m}^3$, and $\nu = 0.2$, the flaw dimension
369 could be estimated as $d = 2.1 \text{ mm}$, the flaw resonance being in that case
370 $f_r \simeq 0.41 \text{ MHz}$. This estimates is in good agreement with the frequency val-
371 ues observed in the frequency domain B-scans in Fig. 8. More information on
372 the material parameters and possible flaw geometry is necessary. We believe
373 however that in the near future the development of a realistic model could
374 lead to quantitative estimates of defect parameters relevant for the structural
375 health assessment of composite structures.

376 **5. Conclusion**

377 We have presented a method enabling ZGV Lamb modes enhancement
378 thanks to the beam shaping of the generation laser, making use of a mask
379 with slits spaced by the ZGV wavelength. First, ZGV Lamb modes have
380 been analyzed in an aluminum plate to validate the possibility to enhance
381 or reduce their amplitude depending on the thermoelastic line sources spac-
382 ing. It has been shown that ZGV Lamb modes interfere constructively when
383 the line sources spacing equals the ZGV wavelength whereas they interfere
384 destructively when the spacing is halved.

385 After the thorough characterization of a composite plate that resulted
386 in the ZGV wavelength determination, the beam-shaping method has been
387 applied to the composite sample. Experimental results demonstrate a ZGV
388 Lamb mode enhancement, hence validating the beam-shaping method also
389 in the case of a composite sample. Finally, by scanning over the sample,
390 the measured signal frequency content near the ZGV frequency has proven
391 its ability to distinguish between healthy zones and an impacted zone of a
392 composite plate, and also to detect flaw zones that are not visually detectable.
393 The next step could possibly be to extract quantitative information from the
394 dominant frequencies of the B-scans compared to those predicted by the
395 mechanical models of the defects.

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